ADAS Subroutine lgasym

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      SUBROUTINE LGASYM(X,DX,FORM,IFORMS,IENDS)
      IMPLICIT REAL*8(A-H,O-Z)
C-----------------------------------------------------------------------
C
C  ************  FORTRAN 77 SUBROUTINE: LGASYM ************************
C
C  PURPOSE: INITIALISES COMMON ARRAYS REQUIRED FOR SPLINING WITH
C  SMOOTH FITTING TO AN ASYMPTOTIC FORM
C
C  LARGER ARRAY DIMENSION VERSION OF NGASYM
C
C  USES LABELLED COMMON /LSPL3/
C
C  IF IENDS=1,MATCHING IS AT FIRST KNOT(GIVEN BY X)
C          =2,MATCHING IS AT  LAST KNOT(GIVEN BY X)
C  ASYMPTOTIC FORMS ARE GIVEN IN THE EXTERNAL FUNCTION FORM(I,X)
C  WHERE I=4*IFORMS-5+2*IENDS POINTS TO FIRST PART OF ASYMP. FORM
C         =4*IFORMS-4+2*IENDS POINTS TO SECOND PART OF ASYMP. FORM
C  THUS A SERIES OF ASYMPTOTIC FORMS MAY BE PRESENT IN FORM
C
C  INPUT
C      COMMON /LSPL3/ PROVIDES INPUT IN VECTOR IEND WHICH SPECIFIES
C                     CHOICE OF END CONDITION AT FIRST IEND(1) OR LAST
C                     IEND(2) KNOT OF SPLINE
C      X=X-VALUE OF END POINT
C      DX=DISPLACEMENT FROM X-VALUE FOR DERIVATIVE EVALUATION
C      FORM=EXTERNAL FUNCTION SPECIFYING ASYMPTOTIC FORMS
C      IFORMS=SELECTED FORM
C      IENDS=1,MATCHING IS AT FIRST KNOT(GIVEN BY X)
C           =2,MATCHING IS AT  LAST KNOT(GIVEN BY X)
C  OUTPUT
C      COMMON /LSPL3/ IS SET BY THIS ROUTINE
C
C AUTHOR:
C
C  ********* H.P. SUMMERS, JET           7 FEB 1989    *************
C
C-----------------------------------------------------------------------
C
C UNIX-IDL CONVERSION:
C
C VERSION: 1.1                          DATE: 07-10-96
C MODIFIED: WILLIAM OSBORN
C               - FIRST CONVERTED.
C
C VERSION: 1.2                          DATE: 15-05-07
C MODIFIED: Allan Whiteford
C               - Updated comments as part of subroutine
C                 documentation production.
C
C-----------------------------------------------------------------------
      COMMON /LSPL3/IEND(2),G(2),AB(4),PQ(12),ABRY(160)
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      IF(IENDS.EQ.1.AND.IEND(1).EQ.4)GO TO 5
      IF(IENDS.EQ.2.AND.IEND(2).EQ.4)GO TO 5
    3 RETURN
    5 I=4*IFORMS-5+2*IENDS
      J=6*IENDS-5
      IC=0
      DX1=1.0D0/DX
   10 PQ(J)=FORM(I,X)
      T1=FORM(I,X+DX)
      T2=FORM(I,X-DX)
      PQ(J+1)=0.5D0*DX1*(T1-T2)
      PQ(J+2)=DX1*DX1*(T1-2.0D0*PQ(J)+T2)
      IC=IC+1
      IF(IC.GT.1)RETURN
      I=I+1
      J=J+3
      GO TO 10
     END
     INTEGER             IENDS,        IFORMS
     REAL*8              DX,           X
```